

## LINEAR INDEPENDENCES IN BOTTLENECK ALGEBRA AND THEIR COHERENCES WITH MATROIDS

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ABSTRACT. Let  $(B, \leq)$  be a dense, linearly ordered set with maximum and minimum element and  $(\oplus, \otimes) = (\max, \min)$ . We say that an  $(m, n)$  matrix  $A = (a_1, a_2, \dots, a_n)$  has: (i) weakly linearly independent (*WLI*) columns if for each vector  $b$  the system  $A \otimes x = b$  has at most one solution; (ii) regularly linearly independent columns (*RLI*) if for each vector  $b$  the system  $A \otimes x = b$  is uniquely solvable; (iii) strongly linearly independent columns (*SLI*) if there exist vectors  $d_1, d_2, \dots, d_r$ ,  $r \geq 0$  such that for each vector  $b$  the system  $(a_1, \dots, a_n, d_1, \dots, d_r) \otimes x = b$  is uniquely solvable. For these linear independences we derive necessary and sufficient conditions which can be checked by polynomial algorithms as well as their coherences with definition of matroids.

### 1. INTRODUCTION

The aim of this paper is to review the results concerning some types of linear independences in Bottleneck algebras (some of them and the others were studied in [1]–[10]) and suggest their coherences with matroidal properties where matroid was formally introduced by Welsh in the following definition.

**Definition.** Let  $\mathcal{S}$  be a finite set and  $\mathcal{I}$  a family of its subsets, called independent sets. Then  $(\mathcal{S}, \mathcal{I})$  is a matroid if

- (i)  $\mathcal{I} \neq \emptyset$  has hereditary property (if  $\mathcal{A} \in \mathcal{I}$  and  $\mathcal{B} \subseteq \mathcal{A}$  then  $\mathcal{B} \in \mathcal{I}$ )
- (ii)  $\mathcal{A}, \mathcal{B} \in \mathcal{I}$  such that  $|\mathcal{A}| = |\mathcal{B}| + 1$  then there exists  $a \in \mathcal{A} \setminus \mathcal{B}$  such that  $\mathcal{B} \cup \{a\} \in \mathcal{I}$ .

If there only (i) is fulfilled we say that  $(\mathcal{S}, \mathcal{I})$  is hereditary system.

A notion of linear independence fulfilling (i), (ii) properties, ensures that all maximal independent sets will have the same cardinality and, hence serves a good starting point for the notion of rank and dimension.

### 2. DEFINITIONS AND NOTATIONS

The quadruple  $\mathcal{B} = (B, \oplus, \otimes, \leq)$ , or  $B$  itself, is called bottleneck algebra (BA) if  $(B, \leq)$  is a nonempty, linearly ordered set with a maximum element (denoted by  $\epsilon$

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and called zero) and a minimum element (denoted by  $\sigma$  and called unit), whereby  $\epsilon \neq \sigma$  and  $\oplus, \otimes$  are binary operations on  $B$  defined by formulas

$$\begin{aligned} a \oplus b &= \max\{a, b\} \\ a \otimes b &= \min\{a, b\}. \end{aligned}$$

In the following we will deal with  $(m, n)$  matrices, and we assume everywhere that  $m$  and  $n$  are given positive integers. For short we denote  $\{1, 2, \dots, n\}$  by  $N$  and  $\{1, 2, \dots, m\}$  by  $M$ . The system of all  $(m, n)$  matrices over  $B$  will be denoted by  $B(m, n)$ . The elements of  $B(m, 1)$  will be called vectors. The elements of  $B$  will be represented by letters of Greek alphabet, a matrix with vectors  $a_1, \dots, a_n$  as its columns will be denoted by  $A = (a_1, \dots, a_n)$  or  $A = (a_{ij})$ . If  $A = (a_{ij}) \in B(m, n)$ ,  $m \geq n$  and  $a_{ij} > \sigma$  for  $i = j$  and  $a_{ij} = \sigma$  otherwise then we say that matrix  $A$  is trapezoidal one and we will denote it as  $A = \text{trap}\{a_{11}, \dots, a_{nn}\}$ . If  $m = n$  we say that the trapezoidal matrix  $A$  is diagonal and denote  $A = \text{diag}\{a_{11}, \dots, a_{nn}\}$ .

Two matrices  $A, B$  are said to be equivalent (abbr.  $A \sim B$ ) if one can be obtained from the other by permutations of its rows and columns. If matrix  $A$  is equivalent to a diagonal matrix then we say  $A$  is a permutation matrix.

Extend  $\oplus, \otimes$  and  $\leq$  to matrices over  $B$  as in conventional algebra. The main results are proved under the assumption of density of the ordering  $\leq$ , that is to say,

$$(\forall x, y \in B) x < y \implies (\exists z \in B) x < z < y.$$

We say that a matrix  $A = (a_1, \dots, a_n) \in B(m, n)$ ,  $n \leq m$  has

- (i) weakly linearly independent (*WLI*) columns if for each vector  $b$  the system  $A \otimes x = b$  has at most one solution;
- (ii) regularly linearly independent (*RLI*) columns if for each vector  $b$  the system  $A \otimes x = b$  is uniquely solvable;
- (iii) strongly linearly independent (*SLI*) columns if there exist vectors  $d_1, \dots, d_r \in B(m, 1)$ ,  $r \geq 0$  such that for each vector  $b$  the system  $(a_1, \dots, a_n, d_1, \dots, d_r) \otimes x = b$  is uniquely solvable.

The definition *WLI* was introduced under the name **2B-independence** in [4], for which was formulated open problem to find necessary and sufficient conditions and checking algorithm for testing of it. *RLI* has a motivation in the conventional linear algebra. The *SLI* is introduced originally in this paper to give a definition of independence with matroidal properties.

### 3. NECESSARY AND SUFFICIENT CONDITIONS FOR LINEAR INDEPENDENCES

Before statement of the main results of this paper we establish some notations. If in  $i$ -th row of  $A$  only one maximum element exists i.e. there exists  $j \in N$  such that  $a_{ij} > a_{is}$  for all  $s \neq j$  we will denote it by  $\pi_i$  and second maximum element

of  $i$ -th row we will denote by  $\tau_i$  i.e.  $\tau_i = \bigoplus_{a_{ij} \neq \pi_i} a_{ij}$ . By  $M_A^*$  we denote the set of all row indices for which only one maximum exists. Denote the sets  $\{j \in M_A^*; \pi_j = a_{ji} > \tau_j > \sigma\}$  and  $\{j \in M_A^*; \pi_j = a_{ji} > \tau_j = \sigma\}$  by  $R_i$  and  $C_i$ , respectively.

**Theorem 1.** *Let  $A \in B(m, n)$ . Then  $A$  has WLI columns if and only if*

- (i) *A contains a permutation submatrix of order  $n$*
- (ii) *A contains a square submatrix of order  $n$  which has in each row and each column exactly one unit entry*
- (iii) *for all  $i \in N' = \{s \in N; R_s \neq \phi\}$*

$$\bigotimes_{j \in R_i} \tau_j \leq \bigoplus_{j \in C_i} \pi_j$$

holds.

*Proof.* Suppose that  $A = (a_{ij}) \in B(m, n)$ .

(i) Denote  $M_j = \{i \in M; a_{ij} > \sigma\}$ . Suppose that a matrix  $A$  is different from the zero-matrix and all zero rows are removed since they do not have any influence on WLI and it implies  $\cup_{k \in N} M_k = M$ . Then it is clear that  $A$  contains a permutation submatrix of order  $n$  if and only if  $\cup_{k \neq j} M_k \neq M$  holds for all  $j \in N$ . Now suppose that  $A$  doesn't contain a permutation submatrix of order  $n$  i.e. according to foregoing discussion there exists  $j \in N$  (say  $j = n$ ) such that  $\cup_{k \neq j} M_k = M$ . Then the system  $A \otimes x = b$  for  $b = (b_1, \dots, b_m)^T \in B(m, 1)$ , and  $b_i = \otimes_{a_{rs} > 0} a_{rs}$  has solutions  $x = (x_1, \dots, x_n)^T$  where  $x_i = b_i$  for  $i = 1, 2, \dots, n-1$  and  $x_n$  is arbitrary element from closed interval  $[\sigma, \otimes_{a_{ij} > \sigma} a_{ij}]$ .

(ii) Suppose that  $A$  contains a column with all entries less than  $\epsilon$ . W.l.o.g. let  $a_{i1} < \epsilon$  for all  $i \in M$ . Set the right-hand side vector  $b$  equal to the first column of  $A$ . It is easy to see that the vector  $x = (\oplus a_{i1}, \sigma, \dots, \sigma)^T$  is a solution of  $A \otimes x = b$ , moreover,  $x' = (\epsilon, \sigma, \dots, \sigma)$  is another solution. Therefore each column of  $A$  must contain at least one unit entry. If a submatrix of order  $n$  with exactly one unit in each row and column does not exist then  $A$  contains a row with at least two unit entries (say) in  $r$ -th and  $s$ -th position for  $r < s, k \leq s \leq n$ . Then system  $A \otimes x = b$  for  $b_i = \oplus_j a_{ij}$  has solutions  $x = (x_1, \dots, x_n)^T, x_i = \epsilon$  for all  $i \neq s$  and  $x_s \in [\oplus_{a_{rs} < \epsilon} a_{rs}, \epsilon]$ .

(iii) The case  $N' = \phi$  is clear since according to (i), (ii) the matrix  $A$  contains a submatrix of order  $n$  equivalent to a  $\text{diag}\{\epsilon, \dots, \epsilon\}$  and consequently it follows that the system  $A \otimes x = b$  has at most one solution for each vector  $b$ . Suppose that there exists  $i \in N'$  (say  $i = 1$ ) such that

$$\bigotimes_{j \in R_1} \tau_j > \bigoplus_{j \in C_1} \pi_j.$$

Then the system  $A \otimes x = b$  for  $b = (b_1, \dots, b_m)^T$  where  $b_i = \tau_i$  for  $i \in R_1, b_i = \pi_i$  for  $i \in C_1$ , otherwise  $b_i = \oplus_j a_{ij}$  has solutions  $x = (x_1, \dots, x_n)^T$  whereby

$x_2 = x_3 = \dots = x_n = \epsilon$  and  $x_1 \in [\oplus_{j \in C_1} \pi_j, \otimes_{j \in R_1} \tau_j]$ . From the density a contradiction follows.

Conversely, we suppose that (i), (ii), (iii) hold. By analysis of cases we will show that for arbitrary vector  $b$  the system  $A \otimes x = b$  either doesn't have solution or  $\oplus_{j \in C_i} \pi_j \leq x_i \leq \otimes_{j \in R_i} \tau_j$  or  $x_i = b_j$  but this fact together with (iii) imply the assertion. Suppose that  $j \in C_i$ . If  $b_j < \pi_j$  then  $x_i = b_j$  and if  $b_j = \pi_j$  then  $x_i \geq \pi_j$  and otherwise the system is not solvable. From foregoing inequality follows that  $\oplus_{j \in C_i} \pi_j \leq x_i$ . The second part we will prove similarly. Let  $j \in R_i$ . If  $\pi_j > b_j > \tau_j$  then  $x_i = b_j$ . If  $b_j \leq \tau_j$  then  $x_i \leq b_j \leq \tau_j$  and again otherwise the system is not solvable. Thus,  $x_i \leq \otimes_{j \in R_i} \tau_j$  and the assertion results.  $\square$

The previous theorem gives a clear hint to the testing of *WLI*-it suffices to look for first and second maxima (in  $O(mn)$  steps) for each  $i \in N'$  to check whether  $\otimes_{j \in R_i} \pi_j \leq \oplus_{j \in C_i} \tau_j$ . For this purpose suppose that rows of  $A$  which have only one maximum element precede the others and denote  $p = (\pi_1, \dots, \pi_j)$ ,  $s = (\tau_1, \dots, \tau_j)$ ,  $j \leq m$  then we are led on finding the sets  $R_i$  and  $C_i$  and then minima and maxima of elements of  $p$  and  $s$  over  $R_i$  and  $C_i$ , respectively (in  $O(2m)$  steps)  $-O(mn) + nO(2m) = O(mn)$ .

**Lemma 1.** *Let  $A \in B(m, n)$ . If  $A$  has *RLI* columns then  $m = n$ .*

*Proof.* Suppose that  $A$  has *RLI* (implies *WLI*) columns. The part (ii) of Proof of Theorem 1 suggests that a matrix  $A$  having *WLI* columns contains a square submatrix of order  $n$  which has in each row and each column exactly one unit entry. For  $n < m$  we will construct a vector  $b$  which implies the system  $A \otimes x = b$  is not solvable. Denote  $b_i = \oplus_j a_{ij}$ . If there exists  $i \in M$  such that  $b_i < \epsilon$  then for  $b' = (b_1, \dots, b_{i-1}, \epsilon, b_{i+1}, \dots, b_m)^T$  the system  $A \otimes x = b'$  doesn't have a solution. If  $b_i = \epsilon$  for all  $i \in M$  then the matrix  $A$  contains a column with at least two unit entries (say) in  $r$ -th and  $s$ -th positions,  $s > n$ . The system  $A \otimes x = b$  is not solvable for  $b = (b_1, \dots, b_m)$  where  $b_i = \sigma$  for all  $i \in M \setminus \{s\}$  and  $b_s = \epsilon$ .  $\square$

**Theorem 2.** *Let  $A \in B(n, n)$ . Then  $A$  has *RLI* columns if and only if  $A \sim \text{diag} \{ \epsilon, \dots, \epsilon \}$ .*

*Proof.* The part "if" is trivial. For a converse, suppose that  $A$  has *RLI* columns then  $A$  has *WLI* columns and according to (i) and (ii) of Theorem 1 we have the assertion.  $\square$

**Theorem 3.** *Let  $A \in B(m, n)$ . Then  $A$  has *SLI* columns if and only if  $A \sim \text{trap} \{ \epsilon, \dots, \epsilon \}$ .*

*Proof.* Suppose that  $A \sim \text{trap} \{ \epsilon, \dots, \epsilon \}$ . Denote for  $i = 1, 2, \dots, r$ ;  $r = m - n$  a vector  $d_i$  which has on  $(n+i)$ -th position unit entry and otherwise entries are equal to  $\sigma$ . Then the matrix  $(a_1, \dots, a_n, d_1, \dots, d_r) \sim \text{diag} \{ \epsilon, \dots, \epsilon \}$  and according to Theorem 2 the system  $(a_1, \dots, a_n, d_1, \dots, d_r) \otimes x = b$  has only one solution for arbitrary vector  $b$ .

Conversely, suppose that there exist vectors  $d_1, \dots, d_r$  such that the system

$$(a_1, \dots, a_n, d_1, \dots, d_r) \otimes x = b$$

is unique solvable. But again using the Theorem 2

$$(a_1, \dots, a_n, d_1, \dots, d_r) \sim \text{diag} \{ \epsilon, \dots, \epsilon \}$$

implies  $A \sim \text{trap} \{ \epsilon, \dots, \epsilon \}$ . □

The last assertions enable to immediately compile an  $O(mn)$  algorithm for testing *RLI* and *SLI* columns of a matrix  $A$ .

4. COHERENCE OF THE LINEAR INDEPENDENCES WITH MATROIDS

Let  $A = (a_1, \dots, a_n) \in B(m, n)$ . If  $A' = (a_{i_1}, \dots, a_{i_k}), \{i_1, \dots, i_k\} \subset \{1, \dots, n\}$  has *WLI* (*RLI*, *SLI*) columns then the system of vectors  $\{a_{i_1}, \dots, a_{i_k}\}$  is said to be *WLI* (*RLI*, *SLI*) subset of  $\mathcal{A}$ .

**Theorem 4.** *Let  $\mathcal{S} = \{a_1, \dots, a_n\}$ . Then  $(\mathcal{S}, \mathcal{I})$  is hereditary system where  $\mathcal{I}$  is a family of *WLI* subsets of  $\mathcal{S}$ .*

*Proof.* Suppose that  $\mathcal{A} = \{a_1, \dots, a_r\} \in \mathcal{I}$  and  $\mathcal{B} = \{a_{i_1}, \dots, a_{i_s}\} \subseteq \mathcal{A}$  and  $A = (a_1, \dots, a_r), B = (a_{i_1}, \dots, a_{i_s})$ .

Denote

$$\begin{aligned} \pi_j &= \bigoplus_{i \in M_A^*} a_{ji}, & \pi'_j &= \bigoplus_{i \in M_B^*} a_{ji} \\ \tau_j &= \bigoplus_{\substack{i \in M_A^* \\ a_{ji} \neq \pi_j}} a_{ji}, & \tau'_j &= \bigoplus_{\substack{i \in M_B^* \\ a_{ji} \neq \pi_j}} a_{ji} \\ R'_t &= \{j \in M_B^*; \pi'_j = a_{jt} > \tau'_j > \sigma\} \end{aligned}$$

and

$$C'_t = \{j \in M_B^*; \pi'_j = a_{jt} > \tau'_j = \sigma\}.$$

Since  $\{i_1, \dots, i_s\} \subseteq \{1, \dots, r\}$  we have  $C_i \subseteq C'_i$  and

$$\bigoplus_{j \in C_i} \pi_j \leq \bigoplus_{j \in C'_i} \pi'_j$$

holds. Therefore for all  $t \in \{i_1, \dots, i_s\} \setminus \{p; R'_p = \phi\}$  is fulfilled either

$$\bigoplus_{j \in C'_t} \pi'_j = \epsilon$$

or

$$\bigotimes_{j \in R'_t} \tau'_j \leq \bigotimes_{j \in R_t} \tau_j.$$

In each of both cases the assertion follows. □

Since the structure of a matrix  $A$  which has *SLI* columns is very simple

$$A \sim \begin{pmatrix} \epsilon & \sigma & \dots & \sigma \\ \sigma & \epsilon & \dots & \sigma \\ \dots & \dots & \dots & \dots \\ \sigma & \sigma & \dots & \epsilon \\ \sigma & \sigma & \dots & \sigma \\ \dots & \dots & \dots & \dots \\ \sigma & \sigma & \dots & \sigma \end{pmatrix}$$

straightforwardly from definitions the following assertion results.

**Theorem 5.** *Let  $\mathcal{S} = \{a_1, \dots, a_n\}$ . Then  $(\mathcal{S}, \mathcal{I})$  is matroid where  $\mathcal{I}$  is a family of *SLI* subset of  $\mathcal{S}$ .*

To summarise the results of this article we give the following table.

Independence	The order	Complexity	Matroid
<i>WLI</i>	$m \geq n$	$O(mn)$	hereditary system
<i>RLI</i>	$m = n$	$O(n^2)$	
<i>SLI</i>	$m \geq n$	$O(mn)$	matroid

**Table 1.**

In conclusion two examples.

**Example 1.** Let  $B = [0, 1] \subset R$  and

$$\mathcal{S} = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0.4 \end{pmatrix}, \begin{pmatrix} 0.3 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \right\}$$

and  $\mathcal{I}$  be a family of *WLI* subsets of  $\mathcal{S}$ . Then this example shows that  $(\mathcal{S}, \mathcal{I})$  is not matroid since  $\mathcal{A} = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0.4 \end{pmatrix}, \begin{pmatrix} 0.3 \\ 1 \\ 0 \end{pmatrix} \right\}$  and  $\mathcal{B} = \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \right\}$  are maximal independent sets and their cardinality are not equal.

**Example 2.** Let  $B = [0, 1] \subset R$

$$\mathcal{S} = \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$$

and  $\mathcal{I}$  be a family of *RLI* subsets of  $\mathcal{S}$ . Then for this example  $(\mathcal{S}, \mathcal{I})$  is not hereditary system since the condition (i) of the definition of matroids is not fulfilled using of Theorem 2.

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