

# UNIFORM APPROXIMATION BY POLYNOMIALS ON REAL NON-DEGENERATE WEIL POLYHEDRON

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**ABSTRACT.** It is proved, that on real non-degenerate polynomial Weil polyhedron  $G$  any function, holomorphic in  $G$  and continuous on its closure, can be uniformly approximated by polynomials.

## 1. INTRODUCTION

A bounded domain  $G \subset \mathbb{C}^n$  is called analytic polyhedron if there are some functions  $\chi_1, \dots, \chi_N$  holomorphic in neighborhoods  $V$  of  $\bar{G}$ , such that

$$(1) \quad G = \{z \in V: |\chi_i(z)| < 1, \quad i = 1, 2, \dots, N\}.$$

The boundary  $\partial G$  of  $G$  consists of the “edges”

$$\sigma_i = \{z \in \partial G: |\chi_i(\zeta)| = 1\}$$

intersecting along the  $k$ -dimensional “ribs”

$$\sigma_{i_1, \dots, i_k} = \sigma_{i_1} \cap \dots \cap \sigma_{i_k}.$$

An analytic polyhedron is called Weil polyhedron if  $N \geq n$ , all edges  $\sigma_i$  are  $(2n - 1)$ -dimensional manifolds and the dimensions of all ribs  $\sigma_{i_1, \dots, i_k}$  ( $2 \leq k \leq n$ ) are at most  $2n - k$ . The union of all these  $n$ -dimensional ribs is

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Received October 27, 2005.

2000 *Mathematics Subject Classification.* Primary 30E05, 41A30, 41A10.

*Key words and phrases.* Holomorphic, polyhedron, approximation,  $\bar{\partial}$ -equation.

the distinguished boundary of  $G$ . The domain  $G$  is called polynomial polyhedron if all determining functions  $\chi_i$  are polynomials in (1).

The main result of this paper (Theorem 3.1) states that if  $G$  is a Weil polyhedron of “general position” in the sense of real analysis (see. Definition 2.1), then any function holomorphic in  $G$  and continuous in  $\overline{G}$  can be uniformly approximated by functions holomorphic in some neighborhoods of  $\overline{G}$ . In the particular case of polynomial polyhedrons, it is proved (Theorem 3.2) that such functions can be approximated by polynomials.

We use some improvement of a method, which is applied in [1] for strictly pseudoconvex domains, and is based on some uniform estimates of solutions of the  $\overline{\partial}$ -equation

$$(2) \quad \overline{\partial}u = g,$$

where  $g = \sum_{k=1}^n g_k d\overline{z}_k$  is a  $\overline{\partial}$ -closed in  $G$  differential form of  $(0, 1)$  type.

We use the following uniform estimate which for  $n = 2$  is obtained in [2] and for arbitrary  $n$  in [3]: *in a real non-degenerate Weil polyhedron the equation (2) has a solution  $u_0(z)$  such that*

$$\|u_0\|_G \leq \gamma \|g\|_G,$$

where  $\gamma = \gamma(G)$  is a constant independent of  $g$  and  $\|\cdot\|_G$  is the sup-norm:

$$\|u\|_G = \sup_{z \in G} u(z), \quad \|g\|_G = \sum_{k=1}^n \|g_k\|_G.$$

Note that there is no theorem on approximation for arbitrary Weil polyhedrons. By a different method, the author [4] has proved an approximation theorem under the complex non-degeneracy condition (meaning that in the general position of complex analysis sense the appropriate edges intersect in the points of distinguished boundary). The class of real non-degenerate polyhedrons is wide enough to provide approximation of any domain

of holomorphy by real non-degenerate polyhedrons, which is not true in the case, when the polyhedrons are complexly non-degenerate, i. e. if their edges intersect in a general position, (in the complex analysis sense).

## 2. LOCAL APPROXIMATION

**Definition 2.1.** We call a polyhedron (1) real non-degenerate if for any collection  $i_1, \dots, i_k$  the matrix

$$(\text{grad}_{\mathbf{R}} |\chi_{i_1}(z)|, \dots, \text{grad}_{\mathbf{R}} |\chi_{i_k}(z)|)$$

attains its maximal rank in all points  $z \in \sigma_{i_1, \dots, i_k}$ .

Here

$$\text{grad}_{\mathbf{R}} f(z) = {}^t(D_1 f(z), \dots, D_n f(z), \overline{D}_1 f(z), \dots, \overline{D}_n f(z)),$$

where  $t$  before the bracket means transposition and

$$D_k f(z) = \frac{\partial f(z)}{\partial z_k}, \quad \overline{D}_k f(z) = \frac{\partial f(z)}{\partial \bar{z}_k}, \quad k = 1, \dots, n.$$

Geometrically, Definition 2.1 means that the edges  $\sigma_{i_1}, \dots, \sigma_{i_k}$  intersect in a general position (in the real analysis sense).

We start by proving the following geometrical property of non-degenerate polyhedrons.

**Proposition 2.2.** *Let  $G$  be a real non-degenerate polyhedron (1) and let  $N \leq 2n$ . Then for any point  $\zeta \in \partial G$  there exist a neighborhood  $B_\zeta$  and a vector  $\nu_\zeta$ , such that  $z + \delta \nu_\zeta \in G$  if  $z \in \overline{B}_\zeta \cap \overline{G}$  for  $\delta > 0$  small enough.*

*Proof.* Denote  $\varphi_i = |\chi_i| - 1$  and assume that  $\zeta \in \partial G$  belongs to the edge  $\sigma_{i_1, \dots, i_k}$ , i.e.  $\varphi_{i_1}(\zeta) = 0, \dots, \varphi_{i_k}(\zeta) = 0$  and

$$(3) \quad \varphi_s(\zeta) < 0, \quad s \neq i_1, \dots, i_k.$$

By  $k \leq 2n$  and our assumptions, the vectors  $\text{grad}_{\mathbf{R}} \varphi_{i_1}(\zeta), \dots, \text{grad}_{\mathbf{R}} \varphi_{i_k}(\zeta)$  are linearly independent. Hence there is a point  $w$  such that

$$\sum_{m=1}^n D_m \varphi_j(\zeta)(w_m - \zeta_m) + \sum_{m=1}^n \bar{D}_m \varphi_j(\zeta)(\bar{w}_m - \bar{\zeta}_m) < 0, \quad j = i_1, \dots, i_k.$$

Due to the continuity of  $D_m \varphi_j(\zeta)$  and  $\bar{D}_m \varphi_j(\zeta)$ , there is a neighborhood  $B_\zeta$ , such that for all points  $z \in \bar{B}_\zeta$  the inequalities

$$(4) \quad \sum_{m=1}^n D_m \varphi_j(z)(w_m - \zeta_m) + \sum_{m=1}^n \bar{D}_m \varphi_j(z)(\bar{w}_m - \bar{\zeta}_m) < 0, \quad j = i_1, \dots, i_k.$$

are true. Let  $z \in \bar{B}_\zeta$ ,  $\delta > 0$ . Then

$$(5) \quad \varphi_j(z + \delta(w - \zeta)) = \varphi_j(z) + 2\delta \text{Re} \sum_{m=1}^n D_m \varphi_j(z)(w_m - \zeta_m) + o(\delta).$$

Denoting  $\nu_\zeta = w - \zeta$  and taking in account that  $\varphi_j(z) \leq 0$  for  $z \in \bar{G}$ , from (4) and (5) we conclude that there exists some  $\delta_0 > 0$  such that for  $\delta < \delta_0$

$$(6) \quad \varphi_j(z + \delta \nu_\zeta) < 0, \quad j = i_1, \dots, i_k, \quad z \in \bar{B}_\zeta \cap \bar{G},$$

By continuity of  $\varphi_j$ , it follows from (3) that one can choose a neighborhood  $B_\zeta$  and a number  $\delta_0$  such that for  $\delta < \delta_0$

$$\varphi_s(z + \delta \nu_\zeta) < 0, \quad s \neq i_1, \dots, i_k, \quad z \in \bar{B}_\zeta \cap \bar{G}.$$

Hence, by (6) we conclude that  $z + \delta \nu_\zeta \in G$ . □

The following lemma relates to local approximation.

**Lemma 2.3.** *There exists a finite covering  $\{U_k: k = 0, 1, \dots, p\}$  of  $\overline{G}$  by open sets, such that for any  $\varepsilon > 0$  and any  $f \in A(G)$  there are holomorphic in  $\overline{U}_k \cap \overline{G}$  functions  $f_k$  for which*

$$(7) \quad \sup_{z \in \overline{U}_k \cap \overline{G}} |f(z) - f_k(z)| < \varepsilon.$$

*Proof.* Let  $f \in A(G)$ ,  $\zeta \in \partial G$  and let  $B_\zeta$  be a neighborhood satisfying the conditions of Proposition 2.2. Then the family of open sets  $\{B_\zeta: \zeta \in \partial G\}$  covers the compact  $\partial G$ , and a finite subcovering  $\{B_{\zeta_k}, k = 1, \dots, p\}$  can be chosen. By Proposition 2.2, the functions  $f(z + \delta\nu_{\zeta_k})$  are holomorphic in  $\overline{B}_{\zeta_k} \cap \overline{G}$  for any  $\delta > 0$  small enough. By uniform continuity of  $f$  in  $\overline{G}$ ,

$$\sup_{z \in \overline{B}_{\zeta_k} \cap \overline{G}} |f(z + \delta\nu_{\zeta_k}) - f(z)| \rightarrow 0 \quad \text{as } \delta \rightarrow 0.$$

Now, choosing a small enough  $\delta > 0$  and denoting  $U_k = B_{\zeta_k}$ ,  $f_k(z) = f(z + \delta\nu_{\zeta_k})$ , we get (7) for  $k = 1, \dots, p$ . Further, we take a compact subdomain  $U_0 \subset G$  such that the system  $\{U_k: k = 0, 1, \dots, p\}$  is an open covering of  $\overline{G}$  and put  $f_0(z) = f(z)$ . Then obviously (7) is true also for  $k = 0$ .  $\square$

### 3. GLOBAL APPROXIMATION

Recalling that a function is said to be holomorphic in a compact set  $K$  if it is holomorphic in some neighborhood of  $K$ , we prove

**Theorem 3.1.** *Let  $G$  be a real non-degenerate Weil polyhedron (1) and let  $N \leq 2n$ . Then any function  $f \in A(G)$  can be uniformly approximated in  $\overline{G}$  by functions holomorphic in  $\overline{G}$ .*

*Proof.* Let  $\varepsilon > 0$ , let  $f \in A(G)$  and let  $\{U_k: k = 0, 1, \dots, p\}$  that of Lemma 2.3. Then by Lemma 2.3, there are functions  $f_k$  holomorphic in  $\overline{U}_k \cap \overline{G}$ , such that

$$(8) \quad \|f_k - f\|_{U_k \cap G} < \varepsilon, \quad k = 0, 1, \dots, p.$$

Let  $\{e_k(z), k = 0, 1, \dots, p\}$  be a partition of unity, i.e. a system of infinitely differentiable, nonnegative, finite functions such that

- (a)  $\text{Supp } e_k \subset U_k, k = 0, 1, \dots, p,$
- (b)  $\sum_{k=0}^p g_k(z) \equiv 1$  in some neighborhood of  $\overline{G}.$

Choose some number  $\eta(\varepsilon) > 0$  small enough to provide the holomorphy of  $f_k$  in the sets

$$V_k = U_k \cap G^\varepsilon, \quad k = 0, 1, \dots, p,$$

where

$$G^\varepsilon = \{z \in V : |\chi_i(z)| < 1 + \eta(\varepsilon), \quad i = 1, 2, \dots, N\}.$$

Obviously

$$(9) \quad \|f_k - f_i\|_{U_k \cap U_i \cap G} \leq \|f_k - f\|_{U_k \cap G} + \|f_i - f\|_{U_i \cap G} < 2\varepsilon, \quad i, k = 0, 1, \dots, p,$$

and, if necessary, taking smaller  $\eta(\varepsilon) > 0$ , by continuity we can get

$$(10) \quad \|f_k - f_i\|_{V_k \cap V_i} < 3\varepsilon, \quad k, i = 0, 1, \dots, p.$$

Now consider the functions

$$(11) \quad h_{ik}(z) = \begin{cases} [f_i(z) - f_k(z)]e_k(z) & \text{if } z \in V_i \cap V_k; \\ 0 & \text{if } z \in V_i \setminus V_k, \end{cases}$$

$$h_i(z) = \sum_{k=0}^p h_{ik}(z).$$

The support of  $g_k(z)$  belongs to the set  $B_k$  (by the assumption (a)), and the set  $V_i^\varepsilon \cap \partial V_k^\varepsilon$  does not intersect with that support. Therefore, the functions  $h_{i_k}^\varepsilon$  and  $h_i^\varepsilon$  are infinitely differentiable in  $V_i^\varepsilon$ , and by (10)

$$(12) \quad |h_i(z)| \leq \sum_{k=0}^p |f_i(z) - f_k(z)| e_k(z) < 3\varepsilon \sum_{k=0}^p g_k(z) = 3\varepsilon.$$

for all  $z \in V_i^\varepsilon \cap \overline{G^\varepsilon}$ . Further, for  $z \in V_i \cap V_j$

$$\begin{aligned} h_i(z) - h_j(z) &= \sum_{k=0}^p [f_i(z) - f_k(z)] e_k(z) - \sum_{k=0}^p [f_j(z) - f_k(z)] e_k(z) \\ &= \sum_{k=0}^p [f_i(z) - f_j(z)] e_k(z) = f_i(z) - f_j(z), \end{aligned}$$

i. e.

$$f_i(z) - h_i(z) = f_j(z) - h_j(z), \quad i, j = 0, 1, \dots, p.$$

This means that the function

$$(13) \quad \psi(z) = f_i(z) - h_i(z) \quad z \in V_i,$$

is globally given in  $G^\varepsilon$  and moreover,  $h \in C^\infty(G^\varepsilon)$ . Using the inequalities (12) and (8), from (13) we obtain

$$|\psi(z) - f(z)| \leq |h_i(z)| + |f_i(z) - f(z)| < 4\varepsilon, \quad z \in U_i \cap \overline{G}.$$

Consequently,

$$(14) \quad \|\psi - f\|_G < 4\varepsilon.$$

Considering the differential form  $g = \bar{\partial}\psi$  in the domain  $G^\varepsilon$ , we see that obviously  $\bar{\partial}g = 0$ . Besides, using (11) and taking in account that  $f_i$  is holomorphic in  $V_i$ , we get

$$(15) \quad g = \bar{\partial}\psi(z) = \bar{\partial}h_i(z) = \sum_{k=0}^p \bar{\partial}h_{ik}(z) = \sum_{k=0}^p (f_i(z) - f_k(z))\bar{\partial}e_k(z)$$

for  $z \in V_i \cap \bar{G}^\varepsilon$ . In addition, denoting  $\gamma_0 = \gamma_0(G) = \max_{0 \leq k \leq p} \|\bar{\partial}e_k\|_{U_k}$ , by (15) and (10) we obtain

$$(16) \quad \|g\|_{G^\varepsilon} \leq \sum_{k=0}^p \|f_i - f_k\|_{G^\varepsilon} \|\bar{\partial}e_k\|_{U_k} \leq 3\gamma_0\varepsilon.$$

Now, let  $u_0$  be a solution of the equation

$$\bar{\partial}u = g$$

in the domain  $G^\varepsilon$ , satisfying the uniform estimate

$$(17) \quad \|u_0\|_{G^\varepsilon} \leq \gamma(G^\varepsilon)\|g\|_{G^\varepsilon}.$$

Then it follows from the proof of the estimate (17) in [2, 3] that the constants  $\gamma(G^\varepsilon)$  are bounded, i.e.

$$(18) \quad \gamma(G^\varepsilon) \leq \gamma = \gamma(G).$$

Besides, (17), (16) and (18) imply

$$(19) \quad \|u_0\|_{G^\varepsilon} \leq 3\gamma_0\gamma\varepsilon.$$

Further, the function  $F(z) = \psi(z) - u_0(z)$  is holomorphic in the domain  $G^\varepsilon$  since  $\bar{\partial}\psi - \bar{\partial}u_0 = g - \bar{\partial}u_0 = 0$ .

Besides, by (14) and (19)

$$(20) \quad \|f - F\|_G \leq \|\psi - f\|_G + \|u_0\|_G < 4\varepsilon + 3\gamma_0\gamma\varepsilon = \gamma_1\varepsilon,$$

where the constant  $\gamma_1$  depends only on  $G$ . □

A stronger assertion than Theorem 3.1 is true for polynomial polyhedrons. Before proving that assertion, recall that a compact set  $K$  is said to be polynomially convex if for any point  $\zeta \notin K$  there is a polynomial  $P_\zeta$  such that  $|P_\zeta(\zeta)| > \max_{z \in K} |P_\zeta(z)|$ . Besides, Oka-Weil's theorem (see., e.g. [5]), states that *any function holomorphic in a neighborhood of a polynomially convex compact set  $K$  can be uniformly approximated on  $K$  by polynomials.*

**Theorem 3.2.** *Let  $G$  be a real non-degenerate polynomial polyhedron (1) and let  $N \leq 2n$ . Then any function  $f \in A(G)$  can be uniformly approximated on  $\bar{G}$  by polynomials.*

*Proof.* Let  $\zeta \notin \bar{G}$ . By the definition of the polyhedron  $G$ ,  $|\chi_i(\zeta)| > 1$  for some  $i$ , which means that  $\bar{G}$  is polynomially convex compact set. It suffices to see that the desired assertion follows from Theorem 3.1 and Oka-Weil's theorem. □

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