# ON INCLUSION PROBLEMS INVOLVING CAPUTO AND HADAMARD FRACTIONAL DERIVATIVES 

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#### Abstract

In this paper, we study the existence of solutions to new inclusion problems involving both Caputo and Hadamard fractional derivatives, and separated boundary conditions. We apply the modern tools of the fixed point theory to study the cases when the multi-valued map (the right hand-side of the inclusions) takes convex as well as non-convex values. Examples illustrating the abstract results are also presented.


## 1. Introduction

Recently, a great interest there has been shown in the area of differential equations and inclusions with non-integer order, since fractional order models are found to be more informative and practical than the ones with integer-order. Fractional order differential operators can describe the memory and hereditary properties of systems and processes in view of their nonlocal characteristic. Many books and monographs are devoted to the development of fractional calculus, for instance, see $[\mathbf{4}, \mathbf{1 8}, \mathbf{2 0}, \mathbf{2 3}, \mathbf{2 5}, \mathbf{2 7}]$ and references therein. For applications of fractional calculus in other fields such as science, engineering and technology, we refer the reader to $[\mathbf{1 0}, \mathbf{1 5}, \mathbf{2 0}, \mathbf{2 2}]$. Differential equations, and inclusions equipped with various boundary conditions are widely investigated by many researchers; for details and development of the topic, for example, see the papers $[\mathbf{1}, \mathbf{2}, \mathbf{3}, \mathbf{5}, \mathbf{1 3}, \mathbf{2 4}]$ and the references cited therein.

In a recent work $[\mathbf{2 6}]$, the authors studied the existence and uniqueness of solutions for the boundary value problems:

$$
\begin{cases}{ }^{C} D^{p}\left({ }^{H} D^{q} x\right)(t)=f(t, x(t)), & t \in J:=[a, b],  \tag{1}\\ \alpha_{1} x(a)+\alpha_{2}\left({ }^{H} D^{q} x\right)(a)=0, & \beta_{1} x(b)+\beta_{2}\left({ }^{H} D^{q} x\right)(b)=0,\end{cases}
$$

[^0]and
\[

$$
\begin{cases}{ }^{H} D^{q}\left({ }^{C} D^{p} x\right)(t)=f(t, x(t)), & t \in J,  \tag{2}\\ \alpha_{1} x(a)+\alpha_{2}\left({ }^{C} D^{p} x\right)(a)=0, & \beta_{1} x(b)+\beta_{2}\left({ }^{C} D^{p} x\right)(b)=0\end{cases}
$$
\]

where ${ }^{C} D^{p}$ and ${ }^{H} D^{q}$ are the Caputo and Hadamard fractional derivatives starting at a point $a>0$, of orders $p$ and $q$, respectively, $0<p, q \leq 1, f J \times \mathbb{R} \rightarrow \mathbb{R}$ is a continuous function and $\alpha_{i}, \beta_{i} \in \mathbb{R}, i=1,2$.

In the present paper, we cover the multi-valued case of the problems addressed in [26]. In precise terms, we investigate the inclusion problems:

$$
\begin{cases}{ }^{C} D^{p}\left({ }^{H} D^{q} x\right)(t) \in F(t, x(t)), & t \in J:=[a, b]  \tag{3}\\ \alpha_{1} x(a)+\alpha_{2}\left({ }^{H} D^{q} x\right)(a)=0, & \beta_{1} x(b)+\beta_{2}\left({ }^{H} D^{q} x\right)(b)=0\end{cases}
$$

and

$$
\begin{cases}{ }^{H} D^{q}\left({ }^{C} D^{p} x\right)(t) \in F(t, x(t)), & t \in J:=[a, b]  \tag{4}\\ \alpha_{1} x(a)+\alpha_{2}\left({ }^{C} D^{p} x\right)(a)=0, & \beta_{1} x(b)+\beta_{2}\left({ }^{C} D^{p} x\right)(b)=0\end{cases}
$$

where $F J \times \mathbb{R} \rightarrow \mathcal{P}(\mathbb{R})$ is a multi-valued $\operatorname{map}(\mathcal{P}(\mathbb{R})$ is the family of all nonempty subsets of $\mathbb{R}$ ) and all other constants are the same as in problems (1) and (2).

We derive the existence results for the inclusion boundary value problems (3) and (4) with the aid of standard fixed point theorems for multi-valued maps. In case of convex valued right-hand side of the inclusions, we use Leray-Schauder nonlinear alternative for multi-valued maps. In the case when $F$ is not necessarily convex valued, we apply nonlinear alternative of Leray-Schauder type for singlevalued maps together with the selection theorem due to Bressan and Colombo for lower semi-continuous maps with decomposable values. Finally, in the case of nonconvex valued right hand side of the inclusions, we apply a fixed point theorem for multivalued contractions due to Covitz and Nadler.

The rest of this paper is organized as follows. In Section 2, we recall some definitions and preliminary results about multi-valued maps and fractional calculus, related to our work. Section 3 contains the main results for the boundary value problems (3) and (4). Illustrative examples are presented in Section 4.

## 2. Preliminaries

In this section, we introduce notations and preliminary facts that are used throughout this paper.

### 2.1. Fractional Calculus

Here, we recall the definitions of the Riemann-Liouville fractional primitive and derivative [18], [25].

Definition 2.1. For an at least $n$-times differentiable function $g[a, \infty) \rightarrow \mathbb{R}$, the Caputo derivative of fractional order $q$ is defined

$$
{ }^{C} D^{q} g(t)=\frac{1}{\Gamma(n-q)} \int_{a}^{t}(t-s)^{n-q-1} g^{(n)}(s) \mathrm{d} s, \quad n-1<q<n, \quad n=[q]+1
$$

where $[q]$ denotes the integer part of the real number $q$.
Definition 2.2. The Riemann-Liouville fractional integral of order $q$ of a function $g[a, \infty) \rightarrow \mathbb{R}$ is defined

$$
{ }^{R L} I^{q} g(t)=\frac{1}{\Gamma(q)} \int_{a}^{t} \frac{g(s)}{(t-s)^{1-q}} \mathrm{~d} s, \quad q>0
$$

provided the integral exists.
Definition 2.3. For an at least $n$-times differentiable function $g[a, \infty) \rightarrow \mathbb{R}$, the Caputo-type Hadamard derivative of fractional order $q$ is defined
${ }^{H} D^{q} g(t)=\frac{1}{\Gamma(n-q)} \int_{a}^{t}\left(\log \frac{t}{s}\right)^{n-q-1} \delta^{n} g(s) \frac{\mathrm{d} s}{s}, \quad n-1<q<n, \quad n=[q]+1$,
where $\delta=t \frac{\mathrm{~d}}{\mathrm{~d} t}, \log (\cdot)=\log _{e}(\cdot)$.
Definition 2.4. The Hadamard fractional integral of order $q$ is defined

$$
{ }^{H} I^{q} g(t)=\frac{1}{\Gamma(q)} \int_{a}^{t}\left(\log \frac{t}{s}\right)^{q-1} g(s) \frac{\mathrm{d} s}{s}, \quad q>0
$$

provided the integral exists.
Lemma 2.5 ([18]). For $q>0$, the general solution of the fractional differential equation ${ }^{C} D^{q} u(t)=0$ is given by

$$
u(t)=c_{0}+c_{1}(t-a)+\ldots+c_{n-1}(t-a)^{n-1}
$$

where $c_{i} \in \mathbb{R}, i=0,1,2, \ldots, n-1(n=[q]+1)$.
In view of Lemma 2.5, it follows that

$$
{ }^{R L} I^{q}\left({ }^{C} D^{q} u\right)(t)=u(t)+c_{0}+c_{1}(t-a)+\ldots+c_{n-1}(t-a)^{n-1}
$$

for some $c_{i} \in \mathbb{R}, i=0,1,2, \ldots, n-1,(n=[q]+1)$.
Lemma 2.6 ([17]). Let $u \in A C_{\delta}^{n}[a, b]$ or $C_{\delta}^{n}[a, b]$, and $q \in \mathbb{C}$, where $C_{\delta}^{n}[a, b]=$ $\left\{g[a, b] \rightarrow \mathbb{C}: \delta^{n-1} g(t) \in A C[a, b]\right\}$. Then

$$
{ }^{H} I^{q}\left({ }^{H} D^{q}\right) u(t)=u(t)-\sum_{k=0}^{n-1} c_{k}(\log (t / a))^{k},
$$

where $c_{i} \in \mathbb{R}, i=0,1,2, \ldots, n-1,(n=[q]+1)$.

In order to define the solution of the boundary value problem (1), we consider its linear variant

$$
\begin{cases}{ }^{C} D^{p}\left({ }^{H} D^{q} x\right)(t)=y(t), & t \in J,  \tag{5}\\ \alpha_{1} x(a)+\alpha_{2}\left({ }^{H} D^{q} x\right)(a)=0, & \beta_{1} x(b)+\beta_{2}\left({ }^{H} D^{q} x\right)(b)=0\end{cases}
$$

where $y \in C(J, \mathbb{R})$.
Lemma 2.7 ([26]). Let

$$
\begin{equation*}
\Omega:=\beta_{1} \alpha_{2}-\alpha_{1}\left(\beta_{1} \frac{(\log (b / a))^{q}}{\Gamma(q+1)}+\beta_{2}\right) \neq 0 \tag{6}
\end{equation*}
$$

Then the unique solution to the separated boundary value problem of sequential Caputo and Hadamard fractional differential equation (5) is given by the integral equation

$$
\begin{align*}
x(t)= & \frac{1}{\Omega}\left(\alpha_{1} \frac{(\log (t / a))^{q}}{\Gamma(q+1)}-\alpha_{2}\right)\left[\beta_{1}{ }^{H} I^{q}\left({ }^{R L} I^{p} y\right)(b)+\beta_{2}{ }^{R L} I^{p} y(b)\right]  \tag{7}\\
& +{ }^{H} I^{q}\left({ }^{R L} I^{p} y\right)(t), \quad t \in J .
\end{align*}
$$

Next, we consider the linear variant of problem (2)

$$
\begin{cases}{ }^{H} D^{q}\left({ }^{C} D^{p} x\right)(t)=z(t), & t \in J,  \tag{8}\\ \alpha_{1} x(a)+\alpha_{2}\left({ }^{C} D^{p} x\right)(a)=0, & \beta_{1} x(b)+\beta_{2}\left({ }^{C} D^{p} x\right)(b)=0\end{cases}
$$

where $z \in C(J, \mathbb{R})$.
Lemma 2.8. [26] Let

$$
\begin{equation*}
\Omega^{*}:=\beta_{1} \alpha_{2}-\alpha_{1}\left(\beta_{1} \frac{(b-a)^{p}}{\Gamma(p+1)}+\beta_{2}\right) \neq 0 \tag{9}
\end{equation*}
$$

Then the unique solution of the separated boundary value problem of sequential Caputo and Hadamard fractional differential equation (8) is given by

$$
\begin{align*}
x(t)= & \frac{1}{\Omega^{*}}\left(\alpha_{1} \frac{(t-a)^{p}}{\Gamma(p+1)}-\alpha_{2}\right)\left[\beta_{1}{ }^{R L} I^{p}\left({ }^{H} I^{q} z\right)(b)+\beta_{2}{ }^{H} I^{q} z(b)\right]  \tag{10}\\
& +{ }^{R L} I^{p}\left({ }^{H} I^{q} z\right)(t), \quad t \in J .
\end{align*}
$$

### 2.2. Multivalued Analysis

Let $C(J, \mathbb{R})$ denote the Banach space of continuous functions $x$ from $J$ into $\mathbb{R}$ with the norm $\|x\|=\sup \{|x(t)|: t \in J\}$. By $L^{1}(J, \mathbb{R})$, we denote the Banach space of Lebesgue integrable functions $y J \rightarrow \mathbb{R}$ endowed with the norm $\|y\|_{L^{1}}=\int_{a}^{b}|y(t)| \mathrm{d} t$.

Let $(X,\|\cdot\|)$ be a Banach space. A multi-valued map $F X \rightarrow \mathcal{P}(X)$ :
(i) is convex (closed) valued if $F(x)$ is convex (closed) for all $x \in X$,
(ii) is bounded on bounded sets if $F(B)=\bigcup_{x \in B} F(x)$ is bounded in $X$ for all bounded set $B$ of $X$, i.e., $\sup _{x \in B}\{\sup \{|y|: y \in F(x)\}\}<\infty$,
(iii) is called upper semi-continuous (u.s.c for short) on $X$ if for each $x_{0} \in X$ the set $F\left(x_{0}\right)$ is nonempty, closed subset of $X$, and for each open set $\mathcal{U}$ of $X$ containing $F\left(x_{0}\right)$, there exists an open neighborhood $\mathcal{V}$ of $x_{0}$ such that $F(\mathcal{V}) \subseteq \mathcal{U}$,
(iv) is said to be completely continuous if $F(B)$ is relatively compact for every bounded subset $B$ of $X$,
(v) has a fixed point if there exists $x \in X$ such that $x \in F(x)$.

For each $y \in C(J, \mathbb{R})$, the set

$$
S_{F, y}=\left\{f \in L^{1}(J, \mathbb{R}): f(t) \in F(t, y) \text { for a.e. } t \in J\right\}
$$

is known as the set of selections for the multi-valued map $F$.
In the following, by $\mathcal{P}_{p}$, we mean a set of all nonempty subsets of $X$ which have the property " $p$," where " $p$ " stands for bounded (b), closed (cl), convex (c), compact (cp), etc. Thus $\mathcal{P}_{c l}(X)=\{Y \in \mathcal{P}(X): Y$ is closed $\}, \mathcal{P}_{b}(X)=\{Y \in$ $\mathcal{P}(X): Y$ is bounded $\}, \mathcal{P}_{c p}(X)=\{Y \in \mathcal{P}(X): Y$ is compact $\}$, and $\mathcal{P}_{c p, c}(X)=$ $\{Y \in \mathcal{P}(X): Y$ is compact and convex $\}$. Let the graph of $G$ be defined by the set $\operatorname{Gr}(G)=\{(x, y) \in X \times Y, y \in G(x)\}$ and recall two useful results concerning closed graphs and upper-semicontinuity.

Lemma 2.9 ([9, Proposition 1.2]). If $G X \rightarrow \mathcal{P}_{c l}(Y)$ is u.s.c., then $\operatorname{Gr}(G)$ is a closed subset of $X \times Y$, i.e., for every sequence $\left\{x_{n}\right\}_{n \in \mathbb{N}} \subset X$ and $\left\{y_{n}\right\}_{n \in \mathbb{N}} \subset Y$, if $x_{n} \rightarrow x_{*}, y_{n} \rightarrow y_{*}$, and $y_{n} \in G\left(x_{n}\right)$ when $n \rightarrow \infty$, then $y_{*} \in G\left(x_{*}\right)$. Conversely, if $G$ is completely continuous and has a closed graph, then it is upper semi-continuous.

Lemma 2.10 ([21]). Let $X$ be a separable Banach space. Let $F[0, T] \times \mathbb{R} \rightarrow$ $\mathcal{P}_{c p, c}(X)$ be an $L^{1}$-Carathéodory multivalued map and let $\Theta$ be a linear continuous mapping from $L^{1}(J, X)$ to $C(J, X)$. Then the operator

$$
\Theta \circ S_{F} C(J, X) \rightarrow \mathcal{P}_{c p, c}(C(J, X)), \quad x \mapsto\left(\Theta \circ S_{F}\right)(x)=\Theta\left(S_{F, x, y}\right)
$$

is a closed graph operator in $C(J, X) \times C(J, X)$.
For more details on multi-valued maps and the proof of the known results cited in this section, we refer the interested reader to the books by Deimling [9], Gorniewicz [12], and Hu and Papageorgiou [16].

## 3. Existence results

Before stating and proving our main existence results for problems (3) and (4), we give the definition of its solution.

Definition 3.1. A function $x \in C(J, \mathbb{R})$ is said to be a solution of the problem (3) [of the problem (4)] if there exists a function $v \in L^{1}(J, \mathbb{R})$ with $v(t) \in F(t, x)$ a.e. on $J$ such that $x$ satisfies the differential equation ${ }^{C} D^{p}\left({ }^{H} D^{q} x\right)(t)=v(t)$ $\left[{ }^{H} D^{q}\left({ }^{C} D^{p} x\right)(t)=v(t)\right]$ on $J$ and the boundary conditions $\alpha_{1} x(a)+\alpha_{2}\left({ }^{H} D^{q} x\right)(a)=$ $0, \beta_{1} x(b)+\beta_{2}\left({ }^{H} D^{q} x\right)(b)=0\left[\alpha_{1} x(a)+\alpha_{2}\left({ }^{C} D^{p} x\right)(a)=0, \beta_{1} x(b)+\beta_{2}\left({ }^{C} D^{p} x\right)(b)=\right.$ $0]$, respectively.

Now, we set some notations for sequential Riemann-Liouville and Hadamard fractional integrals of a function with two variables as

$$
{ }^{H} I^{q}\left({ }^{R L} I^{p}\left(f_{x}\right)\right)(u)=\frac{1}{\Gamma(q) \Gamma(p)} \int_{a}^{u} \int_{a}^{s}\left(\log \frac{u}{s}\right)^{q-1}(s-\tau)^{p-1} f(\tau, x(\tau)) \mathrm{d} \tau \frac{\mathrm{~d} s}{s}
$$

and

$$
{ }^{R L} I^{p}\left({ }^{H} I^{q}\left(f_{x}\right)\right)(u)=\frac{1}{\Gamma(p) \Gamma(q)} \int_{a}^{u} \int_{a}^{s}(u-s)^{p-1}\left(\log \frac{s}{\tau}\right)^{q-1} f(\tau, x(\tau)) \frac{\mathrm{d} \tau}{\tau} \mathrm{~d} s
$$

where $u \in\{t, b\}$. Also, we use these notations for single Riemann-Liouville and Hadamard fractional integrals of orders $p$ and $q$, respectively.

For computational convenience, we put

$$
\begin{align*}
\Omega_{1}= & \frac{1}{|\Omega|}\left(\left|\alpha_{1}\right| \frac{(\log (b / a))^{q}}{\Gamma(q+1)}+\left|\alpha_{2}\right|\right)\left[\left|\beta_{1}\right|{ }^{H} I^{q}\left({ }^{R L} I^{p}(1)\right)(b)+\left|\beta_{2}\right|^{R L} I^{p}(1)(b)\right]  \tag{11}\\
& +{ }^{H} I^{q}\left({ }^{R L} I^{p}(1)\right)(b),
\end{align*}
$$

and

$$
\begin{align*}
\Omega_{1}^{*}= & \frac{1}{\left|\Omega^{*}\right|}\left(\left|\alpha_{1}\right| \frac{(b-a)^{p}}{\Gamma(q+1)}+\left|\alpha_{2}\right|\right)\left[\left|\beta_{1}\right|^{R L} I^{p}\left({ }^{H} I^{q}(1)\right)(b)+\left|\beta_{2}\right|^{H} I^{q}(1)(b)\right]  \tag{12}\\
& +{ }^{R L} I^{p}\left({ }^{H} I^{q}(1)\right)(b) .
\end{align*}
$$

### 3.1. The Upper Semicontinuous case

Our first result, dealing with the convex-valued $F$, is based on Leray-Schauder nonlinear alternative.

Lemma 3.2 (Nonlinear alternative for Kakutani maps [14]). Let E be a Banach space, $C$ a closed convex subset of $E, U$ an open subset of $C$, and $0 \in U$. Suppose that $F \bar{U} \rightarrow \mathcal{P}_{c, c v}(C)$ is a upper semicontinuous compact map. Then either
(i) $F$ has a fixed point in $\bar{U}$, or
(ii) there is $u \in \partial U$ and $\mu \in(0,1)$ with $u \in \mu F(u)$.

Definition 3.3. A multivalued map $F J \times \mathbb{R} \rightarrow \mathcal{P}(\mathbb{R})$ is said to be Carathéodory if
(i) $t \mapsto F(t, x)$ is measurable for each $x \in \mathbb{R}$, and
(ii) $x \mapsto F(t, x)$ is upper semicontinuous for almost all $t \in J$.
(iii) Further a Carathéodory function $F$ is called $L^{1}$-Carathéodory if for each $\rho>0$, there exists $\varphi_{\rho} \in L^{1}\left(J, \mathbb{R}^{+}\right)$such that $\|F(t, x)\|=\sup \{|v|: v \in$ $F(t, x)\} \leq \varphi_{\rho}(t)$ for all $x \in \mathbb{R}$ with $\|x\| \leq \rho$ and for a.e. $t \in J$.
Theorem 3.4. Assume that:
$\left(H_{1}\right) F J \times \mathbb{R} \rightarrow \mathcal{P}_{c p, c}(\mathbb{R})$ is $L^{1}$-Carathéodory
$\left(H_{2}\right)$ there exists a continuous nondecreasing function $\psi[0, \infty) \rightarrow(0, \infty)$ and a function $p \in C\left(J, \mathbb{R}^{+}\right)$such that $\|F(t, x)\|_{\mathcal{P}}:=\sup \{|y|: y \in F(t, x)\} \leq p(t) \psi(\|x\|)$ for each $(t, x) \in J \times \mathbb{R}$,
$\left(H_{3}\right)$ there exists a constant $M>0$ such that

$$
\frac{M}{\Omega_{1} \psi(M)\|p\|}>1
$$

where $\Omega_{1}$ is given by (11).
Then the boundary value problem (3) has at least one solution on $J$.
Proof. Firstly, we transform the problem (3) into a fixed point problem. Consider the multi-valued map: $N C(J, \mathbb{R}) \rightarrow \mathcal{P}(C(J, \mathbb{R}))$ defined by

$$
N(x)=\left\{\begin{array}{l}
h \in C(J, \mathbb{R}): \\
h(t)=\frac{1}{\Omega}\left(\alpha_{1} \frac{(\log (t / a))^{q}}{\Gamma(q+1)}-\alpha_{2}\right)\left[\beta_{1}{ }^{H} I^{q}\left({ }^{R L} I^{p} v\right)(b)\right. \\
\left.\quad+\beta_{2}{ }^{R L} I^{p} v(b)\right]+{ }^{H} I^{q}\left({ }^{R L} I^{p} v\right)(t)
\end{array}\right.
$$

for $v \in S_{F, x}$.
It is clear that fixed points of $N$ are solutions of problem (3). So, we need to show that the operator $N$ satisfies all condition of Lemma 3.2. The proof is given in several steps.
Step 1. $N(x)$ is convex for each $x \in C(J, \mathbb{R})$.
Indeed, if $h_{1}, h_{2}$ belong to $N(x)$, then there exist $v_{1}, v_{2} \in S_{F, x}$ such that for each $t \in J$, we have

$$
\begin{aligned}
h_{i}(t)= & \frac{1}{\Omega}\left(\alpha_{1} \frac{(\log (t / a))^{q}}{\Gamma(q+1)}-\alpha_{2}\right)\left[\beta_{1}{ }^{H} I^{q}\left({ }^{R L} I^{p} v_{i}\right)(b)+\beta_{2}{ }^{R L} I^{p} v_{i}(b)\right] \\
& +{ }^{H} I^{q}\left({ }^{R L} I^{p} v_{i}\right)(t), \quad i=1,2 .
\end{aligned}
$$

Let $0 \leq \theta \leq 1$. Then, for each $t \in J$, we have

$$
\begin{aligned}
& {\left[\theta h_{1}+(1-\theta) h_{2}\right](t)} \\
& =\frac{1}{\Omega}\left(\alpha_{1} \frac{(\log (t / a))^{q}}{\Gamma(q+1)}-\alpha_{2}\right)\left[\beta_{1}{ }^{H} I^{q}\left({ }^{R L} I^{p}\left[\theta v_{1}(s)+(1-\theta) v_{2}(s)\right]\right)(b)\right. \\
& \left.\left.\quad+\beta_{2}{ }^{R L} I^{p}\left[\theta v_{1}(s)+(1-\theta) v_{2}(s)\right]\right)(b)\right]+{ }^{H} I^{q}\left({ }^{R L} I^{p}\left[\theta v_{1}(s)+(1-\theta) v_{2}(s)\right]\right)(t)
\end{aligned}
$$

Since $F$ has convex values ( $S_{F, x}$ is convex), therefore, $\theta h_{1}+(1-\theta) h_{2} \in N(x)$.
Step 2. $N(x)$ maps bounded sets (balls) into bounded sets in $C(J, \mathbb{R})$.
For a positive number $r$, let $B_{r}=\{x \in C(J, \mathbb{R}):\|x\| \leq r\}$ be a bounded ball in $C(J, \mathbb{R})$. Then, for each $h \in N(x), x \in B_{r}$, there exists $v \in S_{F, x}$ such that

$$
\begin{aligned}
h(t)= & \frac{1}{\Omega}\left(\alpha_{1} \frac{(\log (t / a))^{q}}{\Gamma(q+1)}-\alpha_{2}\right)\left[\beta_{1}{ }^{H} I^{q}\left({ }^{R L} I^{p} v\right)(b)+\beta_{2}{ }^{R L} I^{p} v(b)\right] \\
& +{ }^{H} I^{q}\left({ }^{R L} I^{p} v\right)(t)
\end{aligned}
$$

In view of $\left(H_{2}\right)$, for each $t \in J$, we have

$$
\begin{aligned}
|h(t)| \leq & \frac{1}{|\Omega|}\left(\left|\alpha_{1}\right| \frac{(\log (b / a))^{q}}{\Gamma(q+1)}+\left|\alpha_{2}\right|\right)\left[\left|\beta_{1}\right|{ }^{H} I^{q}\left({ }^{R L} I^{p}|v(s)|\right)(b)+\left|\beta_{2}\right|{ }^{R L} I^{p}|v(s)|(b)\right] \\
& +{ }^{H} I^{q}\left({ }^{R L} I^{p}|v(s)|\right)(t)
\end{aligned}
$$

$$
\begin{aligned}
\leq & \left\{\frac{1}{|\Omega|}\left(\left|\alpha_{1}\right| \frac{(\log (b / a))^{q}}{\Gamma(q+1)}+\left|\alpha_{2}\right|\right)\left[\left|\beta_{1}\right|{ }^{H} I^{q}\left({ }^{R L} I^{p}(1)\right)(b)+\left|\beta_{2}\right|^{R L} I^{p}(1)\right)(b)\right] \\
& \left.+{ }^{H} I^{q}\left({ }^{R L} I^{p}(1)\right)(b)\right\}\|p\| \psi(\|x\|) \\
\leq & \Omega_{1}\|p\| \psi(r)
\end{aligned}
$$

which yields

$$
\|h\| \leq \Omega_{1}\|p\| \psi(r)
$$

Step 3. $N(x)$ maps bounded sets into equicontinuous sets of $C(J, \mathbb{R})$.
Let $x$ be any element in $B_{r}$ and $h \in N(x)$. Then there exists a function $v \in S_{F, x}$ such that for each $t \in J$, we have

$$
\begin{aligned}
h(t)= & \frac{1}{\Omega}\left(\alpha_{1} \frac{(\log (t / a))^{q}}{\Gamma(q+1)}-\alpha_{2}\right)\left[\beta_{1}{ }^{H} I^{q}\left({ }^{R L} I^{p} v\right)(b)+\beta_{2}{ }^{R L} I^{p} v(b)\right] \\
& +{ }^{H} I^{q}\left({ }^{R L} I^{p} v\right)(t) .
\end{aligned}
$$

Let $\tau_{1}, \tau_{2} \in J, \tau_{1}<\tau_{2}$. Then

$$
\begin{aligned}
& \left|h\left(\tau_{2}\right)-h\left(\tau_{1}\right)\right| \\
& \leq \frac{\left|\alpha_{1}\right|}{|\Omega| \Gamma(q+1)}\left|\left(\log \left(\tau_{2} / a\right)\right)^{q}-\left(\log \left(\tau_{1} / a\right)\right)^{q}\right|\left\{\left|\beta_{1}\right|^{H} I^{q}\left({ }^{R L} I^{p}(|v|)\right)(b)\right. \\
& \left.\quad+\left|\beta_{2}\right|{ }^{R L} I^{p}(|v|)(b)\right\}+\left|{ }^{H} I^{q}\left({ }^{R L} I^{p}(v)\right)\left(\tau_{2}\right)-{ }^{H} I^{q}\left({ }^{R L} I^{p}(v)\right)\left(\tau_{1}\right)\right| \\
& \leq \\
& \quad \frac{\|p\| \psi(r)\left|\alpha_{1}\right|}{|\Omega| \Gamma(q+1)}\left|\left(\log \left(\tau_{2} / a\right)\right)^{q}-\left(\log \left(\tau_{1} / a\right)\right)^{q}\right|\left\{\left|\beta_{1}\right|{ }^{H} I^{q}\left({ }^{R L} I^{p}(1)\right)(b)\right. \\
& \left.\quad+\left|\beta_{2}\right|^{R L} I^{p}(1)(b)\right\}+\|p\| \psi(r)\left|{ }^{H} I^{q}\left({ }^{R L} I^{p}(1)\right)\left(\tau_{2}\right)-{ }^{H} I^{q}\left({ }^{R L} I^{p}(1)\right)\left(\tau_{1}\right)\right| .
\end{aligned}
$$

The right hand of the above inequality tends to zero independently of $x \in B_{r}$ as $\tau_{1} \rightarrow \tau_{2}$.

As a consequence of Steps 1-3 together with Arzelá-Ascoli theorem, we conclude that $N C(J, \mathbb{R}) \rightarrow \mathcal{P}(C(J, \mathbb{R}))$ is completely continuous.

Since $N(x)$ is completely continuous, in order to prove that it is u.s.c., it is enough to prove that it has a closed graph by Lemma 2.9, which is done in the next step.
Step 4. N has a closed graph.
Let $x_{n} \rightarrow x_{*}, h_{n} \in N\left(x_{n}\right)$, and $h_{n} \rightarrow h_{*}$. We need to show that $h_{*} \in N\left(x_{*}\right)$. Now $h_{n} \in N\left(x_{n}\right)$ implies that there exists $v_{n} \in S_{F, x_{n}}$ such that for each $t \in J$,

$$
\begin{aligned}
h_{n}(t)= & \frac{1}{\Omega}\left(\alpha_{1} \frac{(\log (t / a))^{q}}{\Gamma(q+1)}-\alpha_{2}\right)\left[\beta_{1}{ }^{H} I^{q}\left({ }^{R L} I^{p} v_{n}\right)(b)+\beta_{2}{ }^{R L} I^{p} v_{n}(b)\right] \\
& +{ }^{H} I^{q}\left({ }^{R L} I^{p} v_{n}\right)(t) .
\end{aligned}
$$

Therefore, we must show that there exists $v_{*} \in S_{F, x_{*}}$ such that for each $t \in J$,

$$
\begin{aligned}
h_{*}(t)= & \frac{1}{\Omega}\left(\alpha_{1} \frac{(\log (t / a))^{q}}{\Gamma(q+1)}-\alpha_{2}\right)\left[\beta_{1}{ }^{H} I^{q}\left({ }^{R L} I^{p} v_{*}\right)(b)+\beta_{2}{ }^{R L} I^{p} v_{*}(b)\right] \\
& +{ }^{H} I^{q}\left({ }^{R L} I^{p} v_{*}\right)(t) .
\end{aligned}
$$

Consider the continuous linear operator $\Theta L^{1}(J, \mathbb{R}) \rightarrow C(J, \mathbb{R})$ defined by

$$
\begin{aligned}
v \rightarrow \Theta(v)(t)=\frac{1}{\Omega} & \left(\alpha_{1} \frac{(\log (t / a))^{q}}{\Gamma(q+1)}-\alpha_{2}\right)\left[\beta_{1}{ }^{H} I^{q}\left({ }^{R L} I^{p} v\right)(b)+\beta_{2}{ }^{R L} I^{p} v(b)\right] \\
& +{ }^{H} I^{q}\left({ }^{R L} I^{p} v\right)(t)
\end{aligned}
$$

Observe that $\left\|h_{n}(t)-h_{*}(t)\right\| \rightarrow 0$ as $n \rightarrow \infty$, and thus it follows by Lemma 2.10 that $\Theta \circ S_{F, x}$ is a closed graph operator.
Moreover, we have

$$
h_{n} \in \Theta\left(S_{F, x_{n}}\right)
$$

Since $x_{n} \rightarrow x_{*}$, Lemma 2.10 implies that

$$
\begin{aligned}
h_{*}(t)= & \frac{1}{\Omega}\left(\alpha_{1} \frac{(\log (t / a))^{q}}{\Gamma(q+1)}-\alpha_{2}\right)\left[\beta_{1}{ }^{H} I^{q}\left({ }^{R L} I^{p} v_{*}\right)(b)+\beta_{2}{ }^{R L} I^{p} v_{*}(b)\right] \\
& +{ }^{H} I^{q}\left({ }^{R L} I^{p} v_{*}\right)(t)
\end{aligned}
$$

for some $v_{*} \in S_{F, x_{*}}$
Step 5. We show there exists an open set $U \subseteq C(J, \mathbb{R})$ with $x \notin \lambda N(x)$ for any $\lambda \in(0,1)$ and all $x \in \partial U$.

Let $\lambda \in(0,1)$ and $x \in \lambda N(x)$. Then there exists $v \in L^{1}(J, \mathbb{R})$ with $v \in S_{F, x}$ such that for $t \in J$, we have

$$
\begin{aligned}
x(t)= & \lambda \frac{1}{\Omega}\left(\alpha_{1} \frac{(\log (t / a))^{q}}{\Gamma(q+1)}-\alpha_{2}\right)\left[\beta_{1}{ }^{H} I^{q}\left({ }^{R L} I^{p} v\right)(b)+\beta_{2}{ }^{R L} I^{p} v(b)\right] \\
& +\lambda^{H} I^{q}\left({ }^{R L} I^{p} v\right)(t)
\end{aligned}
$$

In view of $\left(H_{2}\right)$, for each $t \in J$, we have

$$
\begin{aligned}
|x(t)| \leq & \frac{1}{|\Omega|}\left(\left|\alpha_{1}\right| \frac{(\log (b / a))^{q}}{\Gamma(q+1)}+\left|\alpha_{2}\right|\right)\left[\left|\beta_{1}\right|{ }^{H} I^{q}\left({ }^{R L} I^{p}|v(s)|\right)(b)\right. \\
& \left.+\left|\beta_{2}\right|{ }^{R L} I^{p}|v(s)|(b)\right]+{ }^{H} I^{q}\left({ }^{R L} I^{p}|v(s)|\right)(t) \\
\leq & \left\{\frac { 1 } { | \Omega | } ( | \alpha _ { 1 } | \frac { ( \operatorname { l o g } ( b / a ) ) ^ { q } } { \Gamma ( q + 1 ) } + | \alpha _ { 2 } | ) \left[\left|\beta_{1}\right|{ }^{H} I^{q}\left({ }^{R L} I^{p}(1)\right)(b)\right.\right. \\
& \left.\left.+\left|\beta_{2}\right|{ }^{R L} I^{p}(1)(b)\right]+{ }^{H} I^{q}\left({ }^{R L} I^{p}(1)\right)(b)\right\}\|p\| \psi(\|x\|) \\
= & \Omega_{1}\|p\| \psi(\|x\|)
\end{aligned}
$$

which can alternatively be written as

$$
\frac{\|x\|}{\Omega_{1} \psi(\|x\|)\|p\|} \leq 1
$$

In view of $\left(H_{3}\right)$, there exists $M$ such that $\|x\| \neq M$. Let us set

$$
U=\{x \in C(J, \mathbb{R}):\|x\|<M\}
$$

The operator $N \bar{U} \rightarrow \mathcal{P}(C(J, \mathbb{R}))$ is a compact multi-valued map, u.s.c. with convex closed values. From the choice of $U$, there is no $x \in \partial U$ such that $x \in \lambda N(x)$ for
some $\lambda \in(0,1)$. Consequently, by the nonlinear alternative of Leray-Schauder type (Lemma 3.2), we deduce that $N$ has a fixed point $x \in \bar{U}$ which is a solution of the boundary value problem (3). This completes the proof.

Corollary 3.5. Assume that $\left(H_{1}\right),\left(H_{2}\right)$, and the following condition hold:
$\left(H_{3}\right)^{*}$ There exists a constant $M^{*}>0$ such that

$$
\frac{M^{*}}{\Omega_{1}^{*} \psi(M)\|p\|}>1
$$

where $\Omega_{1}^{*}$ is given by (12).
Then the boundary value problem (4) has at least one solution on $J$.

### 3.2. The lower semicontinuous case

In this subsection, we study the case when $F$ is not necessarily convex valued by applying the nonlinear alternative of Leray-Schauder type together with a selection theorem by Bressan and Colombo [6] for lower semi-continuous maps with decomposable values.

Definition 3.6. Let $A$ be a subset of $I \times \mathbb{R}$. $A$ is $\mathcal{L} \otimes \mathcal{B}$ measurable if $A$ belongs to the $\sigma$-algebra generated by all sets of the form $\mathcal{J} \times \mathcal{D}$, where $\mathcal{J}$ is Lebesgue measurable in $I$ and $\mathcal{D}$ is Borel measurable in $\mathbb{R}$.

Definition 3.7. A subset $\mathcal{A}$ of $L^{1}(I, \mathbb{R})$ is decomposable if for all $u, v \in \mathcal{A}$ and measurable $\mathcal{J} \subset I$, the function $u \chi_{\mathcal{J}}+v \chi_{I-\mathcal{J}} \in \mathcal{A}$, where $\chi_{\mathcal{J}}$ stands for the characteristic function of $\mathcal{J}$.

Lemma $3.8([\mathbf{6}])$. Let $Y$ be a separable metric space and let $N Y \rightarrow \mathcal{P}\left(L^{1}(I, \mathbb{R})\right)$ be a lower semi-continuous (l.s.c.) multivalued operator with nonempty closed and decomposable values. Then $N$ has a continuous selection, that is, there exists a continuous function (single-valued) $h Y \rightarrow L^{1}(I, \mathbb{R})$ such that $h(x) \in N(x)$ for every $x \in Y$.

Theorem 3.9. Assume that $\left(H_{2}\right),\left(H_{3}\right)$, and the following condition hold:
$\left(H_{4}\right) F J \times \mathbb{R} \rightarrow \mathcal{P}(\mathbb{R})$ is a nonempty compact-valued multivalued map such that
(a) $(t, x) \longmapsto F(t, x)$ is $\mathcal{L} \otimes \mathcal{B}$ measurable,
(b) $x \longmapsto F(t, x)$ is lower semicontinuous for each $t \in J$.

Then the boundary value problem (3) has at least one solution on $J$.
Proof. It follows from $\left(H_{2}\right)$ and $\left(H_{4}\right)$ that $F$ is of l.s.c. type [11]. Then, by Lemma 3.8, there exists a continuous function $v C^{1}(J, \mathbb{R}) \rightarrow L^{1}(J, \mathbb{R})$ such that $v(x) \in \mathcal{F}(x)$ for all $v \in C(J, \mathbb{R})$, where $\mathcal{F} C(J \times \mathbb{R}) \rightarrow \mathcal{P}\left(L^{1}(J, \mathbb{R})\right)$ is the Nemytskii operator associated with $F$ defined by

$$
\mathcal{F}(v)=\left\{w \in L^{1}(J, \mathbb{R}): w(t) \in F(t, v(t)) \text { for a.e. } t \in J\right\}
$$

Consider the problem

$$
\begin{cases}{ }^{C} D^{p}\left({ }^{H} D^{q} x\right)(t)=f(x(t)), & t \in J,  \tag{13}\\ \alpha_{1} x(a)+\alpha_{2}\left({ }^{H} D^{q} x\right)(a)=0, & \beta_{1} x(b)+\beta_{2}\left({ }^{H} D^{q} x\right)(b)=0\end{cases}
$$

Note that $x$ is a solution to the boundary value problem (3) if $x \in C^{1}(J, \mathbb{R})$ is a solution of (13). In order to transform the problem (13) into a fixed point problem, we define an operator $\bar{N}$

$$
\begin{aligned}
\bar{N} x(t)= & \frac{1}{\Omega}\left(\alpha_{1} \frac{(\log (t / a))^{q}}{\Gamma(q+1)}-\alpha_{2}\right)\left[\beta _ { 1 } { } ^ { H } I ^ { q } \left({ }^{R L} I^{p} f(x(s))(b)\right.\right. \\
& \left.+\beta_{2}{ }^{R L} I^{p} f(x(s))(b)\right]+{ }^{H} I^{q}\left({ }^{R L} I^{p} f(x(s))(t) .\right.
\end{aligned}
$$

It can easily shown that $\bar{N}$ is continuous and completely continuous. The remaining part of the proof is similar to that of Theorem 3.4. So, we omit it. This completes the proof.

Corollary 3.10. Assume that $\left(H_{2}\right),\left(H_{3}\right)^{*}$, and $\left(H_{4}\right)$ hold. Then the boundary value problem (4) has at least one solution on $J$.

### 3.3. The Lipschitz case

Here, we prove the existence of solutions for the boundary value problem (3) with a nonconvex valued right hand side by applying a fixed point theorem for multivalued map due to Covitz and Nadler [8].

Let $(X, d)$ be a metric space induced from the normed space $(X ;\|\cdot\|)$. Consider $H_{d} \mathcal{P}(X) \times \mathcal{P}(X) \rightarrow \mathbb{R} \cup\{\infty\}$ given by

$$
H_{d}(A, B)=\max \left\{\sup _{a \in A} d(a, B), \sup _{b \in B} d(A, b)\right\},
$$

where $d(A, b)=\inf _{a \in A} d(a ; b)$ and $d(a, B)=\inf _{b \in B} d(a ; b)$. Then $\left(\mathcal{P}_{b, c l}(X), H_{d}\right)$ is a metric space (see [19]).

Definition 3.11. A multivalued operator $N X \rightarrow \mathcal{P}_{c l}(X)$ is called
(a) $\theta$-Lipschitz if and only if there exists $\theta>0$ such that

$$
H_{d}(N(x), N(y)) \leq \theta d(x, y) \quad \text { for each } x, y \in X
$$

(b) a contraction if and only if it is $\theta$-Lipschitz with $\theta<1$.

Lemma 3.12 ([8]). Let $(X, d)$ be a complete metric space. If $N X \rightarrow \mathcal{P}_{c l}(X)$ is a contraction, then Fix $N \neq \emptyset$.

Theorem 3.13. Assume that the following conditions hold:
$\left(H_{5}\right) F J \times \mathbb{R} \rightarrow \mathcal{P}_{c p}(\mathbb{R})$ is such that $F(\cdot, x) J \rightarrow \mathcal{P}_{c p}(\mathbb{R})$ is measurable for each $x \in \mathbb{R}$,
$\left(H_{6}\right) H_{d}(F(t, x), F(t, \bar{x})) \leq m(t)|x-\bar{x}|$ for almost all $t \in J$ and $x, \bar{x} \in \mathbb{R}$ with $m \in C\left(J, \mathbb{R}^{+}\right)$and $d(0, F(t, 0)) \leq m(t)$ for almost all $t \in J$.
Then the boundary value problem (3) has at least one solution on $J$ if

$$
\Omega_{1}\|m\|<1
$$

where $\Omega_{1}$ is given by (11).

Proof. We transform the boundary value problem (3) into a fixed point problem by considering the operator $N C(J, \mathbb{R}) \rightarrow \mathcal{P}(C(J, \mathbb{R}))$ defined in the beginning of the proof of Theorem 3.2. The proof will be complete once it is shown that the operator $N$ satisfies the assumptions of Lemma 3.12. This established in two steps. Step I. $N(x)$ is nonempty and closed for every $v \in S_{F, x}$.

Since the set-valued map $F(\cdot, x(\cdot))$ is measurable by the measurable selection theorem (e.g., $[\mathbf{7}$, Theorem III.6]), it admits a measurable selection $v J \rightarrow \mathbb{R}$. Moreover, by the assumption $\left(H_{6}\right)$, we have

$$
|v(t)| \leq m(t)+m(t)|x(t)|
$$

i.e., $v \in L^{1}(J, \mathbb{R})$, and hence $F$ is integrably bounded. Therefore, $S_{F, x} \neq \emptyset$.

Next, we show that $N(x)$ is closed for each $x \in C(J, \mathbb{R})$. Let $\left\{u_{n}\right\}_{n \geq 0} \in N(x)$ be such that $u_{n} \rightarrow u,(n \rightarrow \infty)$ in $C(J, \mathbb{R})$. Then $u \in C(J, \mathbb{R})$ and there exists $v_{n} \in S_{F, x_{n}}$ such that for each $t \in J$,

$$
\begin{aligned}
u_{n}(t)= & \frac{1}{\Omega}\left(\alpha_{1} \frac{(\log (t / a))^{q}}{\Gamma(q+1)}-\alpha_{2}\right)\left[\beta_{1}{ }^{H} I^{q}\left({ }^{R L} I^{p} v_{n}\right)(b)+\beta_{2}{ }^{R L} I^{p} v_{n}(b)\right] \\
& +{ }^{H} I^{q}\left({ }^{R L} I^{p} v_{n}\right)(t)
\end{aligned}
$$

As $F$ has compact values, we pass onto a subsequence (if necessary) to obtain that $v_{n}$ converges to $v$ in $L^{1}(J, \mathbb{R})$. Thus $v \in S_{F, x}$ and for each $t \in J$, we have

$$
\begin{aligned}
u_{n}(t) \rightarrow v(t)= & \frac{1}{\Omega}\left(\alpha_{1} \frac{(\log (t / a))^{q}}{\Gamma(q+1)}-\alpha_{2}\right)\left[\beta_{1}{ }^{H} I^{q}\left({ }^{R L} I^{p} v\right)(b)+\beta_{2}{ }^{R L} I^{p} v(b)\right] \\
& +{ }^{H} I^{q}\left({ }^{R L} I^{p} v\right)(t)
\end{aligned}
$$

Hence $u \in N(x)$.
Step II. There exists $0<\theta<1 \quad\left(\theta=\Omega_{1}\|m\|\right)$ such that

$$
H_{d}(N(x), N(\bar{x})) \leq \theta\|x-\bar{x}\| \quad \text { for each } x, \bar{x} \in C(J, \mathbb{R})
$$

Let $x, \bar{x} \in C(J, \mathbb{R})$ and $h_{1} \in N(x)$. Then there exists $v_{1}(t) \in F(t, x(t))$ such that, for each $t \in J$

$$
\begin{aligned}
h_{1}(t)= & \frac{1}{\Omega}\left(\alpha_{1} \frac{(\log (t / a))^{q}}{\Gamma(q+1)}-\alpha_{2}\right)\left[\beta_{1}{ }^{H} I^{q}\left({ }^{R L} I^{p} v_{1}\right)(b)+\beta_{2}{ }^{R L} I^{p} v_{1}(b)\right] \\
& +{ }^{H} I^{q}\left({ }^{R L} I^{p} v_{1}\right)(t) .
\end{aligned}
$$

By $\left(H_{6}\right)$, we have

$$
H_{d}(F(t, x), F(t, \bar{x})) \leq m(t)|x(t)-\bar{x}(t)| .
$$

So, there exists $w(t) \in F(t, \bar{x}(t))$ such that

$$
\left|v_{1}(t)-w\right| \leq m(t)|x(t)-\bar{x}(t)|, \quad t \in J
$$

Define $U J \rightarrow \mathcal{P}(\mathbb{R})$ by

$$
U(t)=\left\{w \in \mathbb{R}:\left|v_{1}(t)-w\right| \leq m(t)|x(t)-\bar{x}(t)|\right\}
$$

Since the multivalued operator $U(t) \cap F(t, \bar{x}(t)$ ) is measurable ([7, Proposition III.4]), there exists a function $v_{2}(t)$ which is a measurable selection for $U$. So $v_{2}(t) \in F(t, \bar{x}(t))$ and for each $t \in J$, we have $\left|v_{1}(t)-v_{2}(t)\right| \leq m(t)|x(t)-\bar{x}(t)|$.

For each $t \in J$, let us define

$$
\begin{aligned}
h_{2}(t)= & \frac{1}{\Omega}\left(\alpha_{1} \frac{(\log (t / a))^{q}}{\Gamma(q+1)}-\alpha_{2}\right)\left[\beta_{1}{ }^{H} I^{q}\left({ }^{R L} I^{p} v_{2}\right)(b)+\beta_{2}{ }^{R L} I^{p} v_{2}(b)\right] \\
& +{ }^{H} I^{q}\left({ }^{R L} I^{p} v_{2}\right)(t) .
\end{aligned}
$$

In consequence, we get

$$
\begin{aligned}
\left|h_{1}(t)-h_{2}(t)\right| \leq & \frac{1}{|\Omega|}\left(\left|\alpha_{1}\right| \frac{(\log (b / a))^{q}}{\Gamma(q+1)}+\left|\alpha_{2}\right|\right)\left[\left|\beta_{1}\right|{ }^{H} I^{q}\left({ }^{R L} I^{p}\left|v_{2}(s)-v_{1}(s)\right|\right)(b)\right. \\
& \left.+\left|\beta_{2}\right|{ }^{R L} I^{p}\left|v_{2}(s)-v_{1}(s)\right|(b)\right]+{ }^{H} I^{q}\left({ }^{R L} I^{p}\left|v_{2}(s)-v_{1}(s)\right|\right)(b) \\
\leq & \left\{\frac { 1 } { | \Omega | } ( | \alpha _ { 1 } | \frac { ( \operatorname { l o g } ( b / a ) ) ^ { q } } { \Gamma ( q + 1 ) } + | \alpha _ { 2 } | ) \left[\left|\beta_{1}\right|{ }^{H} I^{q}\left({ }^{R L} I^{p}(1)\right)(b)\right.\right. \\
& \left.\left.\left.+\left|\beta_{2}\right|{ }^{R L}(1)\right)(b)\right]+{ }^{H} I^{q}\left({ }^{R L}(1)\right)(b)\right\}\|m\|\|x-\bar{x}\| .
\end{aligned}
$$

Hence

$$
\left\|h_{1}-h_{2}\right\| \leq \Omega_{1}\|m\|\|x-\bar{x}\| .
$$

Analogously, interchanging the roles of $x$ and $\bar{x}$, we obtain

$$
H_{d}(N(x), N(\bar{x})) \leq \Omega_{1}\|m\|\|x-\bar{x}\| .
$$

Since $N$ is a contraction, it follows by Lemma 3.12 that $N$ has a fixed point $x$ which is a solution of (3). This completes the proof.

Corollary 3.14. Assume that $\left(H_{5}\right)$ and $\left(H_{6}\right)$ are satisfied. Then the boundary value problem (4) has at least one solution on $J$, provided that $\Omega_{1}^{*}\|m\|<1$, where $\Omega_{1}^{*}$ is given by (12).

## 4. Examples

Example 4.1. Consider the following Caputo and Hadamard fractional differential inclusion with separated boundary conditions

$$
\begin{cases}{ }^{C} D^{1 / 2}\left({ }^{H} D^{2 / 3} x\right) \in F(t, x(t)), & t \in\left[\frac{1}{3}, \frac{8}{3}\right]  \tag{14}\\ \frac{3}{4} x\left(\frac{1}{3}\right)+\frac{2}{5}\left({ }^{H} D^{2 / 3} x\right)\left(\frac{1}{3}\right)=0, & \frac{1}{6} x\left(\frac{8}{3}\right)+\frac{5}{7}\left({ }^{H} D^{2 / 3} x\right)\left(\frac{8}{3}\right)=0\end{cases}
$$

Here $p=1 / 2, q=2 / 3, a=1 / 3, b=8 / 3, \alpha_{1}=3 / 4, \alpha_{2}=2 / 5, \beta_{1}=1 / 6$, and $\beta_{2}=5 / 7$. Using the given values, we find that $|\Omega| \approx 0.6946321201,{ }^{R L} I^{1 / 2}(1)(8 / 3)$ $\approx 1.723627649,{ }^{H} I^{2 / 3}\left({ }^{R L} I^{1 / 2}(1)\right)(8 / 3) \approx 1.908401883$, and $\Omega_{1} \approx 5.819227275$.
(i) Consider the multivalued map $F[1 / 3,8 / 3] \times \mathbb{R} \rightarrow \mathcal{P}(\mathbb{R})$ given by

$$
\begin{equation*}
x \rightarrow F(t, x)=\left[\frac{\mathrm{e}^{-x^{2}}}{2\left(25+t^{2}\right)}, \frac{1}{17+3 t}\left(\frac{|x|^{3}}{2(1+|x|)}+\frac{x^{2}}{1+|x|}+\frac{1}{2}\right)\right] \tag{15}
\end{equation*}
$$

Clearly the multivalued map $F$ satisfies condition $\left(H_{1}\right)$ and that

$$
\|F(t, x)\|_{\mathcal{P}} \leq \frac{1}{17+3 t}\left(\frac{1}{2} x^{2}+|x|+\frac{1}{2}\right):=p(t) \psi(|x|)
$$

which yields $\|p\|=1 / 18$ and $\psi(\|x\|)=(1 / 2)\|x\|^{2}+\|x\|+(1 / 2)$. Therefore, the condition $\left(H_{2}\right)$ is fulfilled. By direct computation, there exists a constant $M \in(0.254319013,3.932069367)$ satisfying condition $\left(H_{3}\right)$. Hence all assumptions of Theorem 3.4 hold and hence the problem (14) with $F$ given by (15) has at least one solution on $[1 / 3,8 / 3]$.
(ii) Let the multivalued map $F[1 / 3,8 / 3] \times \mathbb{R} \rightarrow \mathcal{P}(\mathbb{R})$ be defined by

$$
\begin{equation*}
x \rightarrow F(t, x)=\left[0, \frac{1}{8+12 t}\left(\frac{x^{2}+2|x|}{1+|x|}\right)+\frac{1}{40}\right] . \tag{16}
\end{equation*}
$$

Choosing $m(t)=2 /(8+12 t)$, we find that $H_{d}(F(t, x), F(t, y)) \leq m(t)|x-y|$ and $d(0, F(t, 0))=1 / 40 \leq m(t)$ for almost all $t \in[1 / 3,8 / 3]$. In addition we get $\|m\|=1 / 6$ which leads to $\Omega_{1}\|m\| \approx 0.9698712125<1$. By the conclusion of Theorem 3.13, the problem (14) with $F$ given by (16), has at least one solution on $[1 / 3,8 / 3]$.

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